

INDICATIVE SYLLABUS: Experienced Engineer

Executive Aptitude Test (50 Questions)

Executive Aptitude Test is common to all disciplines. This part will be consists of 50 objective type questions on:

01. Verbal Ability/General English
02. Quantitative Aptitude
03. Reasoning Ability

Technical/Subject Knowledge Test (70 Questions)

ELECTRICAL DISCIPLINE

Section 1: Engineering Mathematics

Linear Algebra: Matrix Algebra, Systems of linear equations, Eigenvalues, Eigenvectors.

Calculus: Mean value theorems, Theorems of integral calculus, Evaluation of definite and improper integrals, Partial Derivatives, Maxima and minima, Multiple integrals, Fourier series, Vector identities, Directional derivatives, Line integral, Surface integral, Volume integral, Stokes's theorem, Gauss's theorem, Green's theorem.

Differential equations: First order equations (linear and nonlinear), Higher order linear differential equations with constant coefficients, Method of variation of parameters, Cauchy's equation, Euler's equation, Initial and boundary value problems, Partial Differential Equations, Method of separation of variables.

Complex variables: Analytic functions, Cauchy's integral theorem, Cauchy's integral formula, Taylor series, Laurent series, Residue theorem, Solution integrals.

Probability and Statistics: Sampling theorems, Conditional probability, Mean, Median, Mode, Standard Deviation, Random variables, Discrete and Continuous distributions, Poisson distribution, Normal distribution, Binomial distribution, Correlation analysis, Regression analysis.

Numerical Methods: Solutions of nonlinear algebraic equations, Single and Multi-step methods for differential equations.

Transform Theory: Fourier Transform, Laplace Transform, z-Transform.

Electrical Engineering

Section 2: Electric Circuits

Network graph, KCL, KVL, Node and Mesh analysis, Transient response of dc and ac networks, Sinusoidal steady-state analysis, Resonance, Passive filters, Ideal current and voltage sources, Thevenin's theorem, Norton's theorem, Superposition theorem, Maximum power transfer theorem, Two-port networks, Three phase circuits, Power and power factor in ac circuits.

Section 3: Electromagnetic Fields

Coulomb's Law, Electric Field Intensity, Electric Flux Density, Gauss's Law, Divergence, Electric field and potential due to point, line, plane and spherical charge distributions, Effect of dielectric medium, Capacitance of simple configurations, Biot-Savart's law, Ampere's law, Curl, Faraday's law, Lorentz force, Inductance, Magnetomotive force, Reluctance, Magnetic circuits, Self and Mutual inductance of simple configurations.

Section 4: Signals and Systems

Representation of continuous and discrete-time signals, Shifting and scaling operations, Linear Time Invariant and Causal systems, Fourier series representation of continuous periodic signals, Sampling theorem, Applications of Fourier Transform, Laplace Transform and z-Transform.

Section 5: Electrical Machines

Single phase transformer: equivalent circuit, phasor diagram, open circuit and short circuit tests, regulation and efficiency; Three phase transformers: connections, parallel operation; Auto-transformer, Electromechanical energy conversion principles, DC machines: separately excited, series and shunt, motoring and generating mode of operation and their characteristics, starting and speed control of dc motors; Three phase induction motors: principle of operation, types, performance, torque-speed characteristics, no-load and blocked rotor tests, equivalent circuit, starting and speed control; Operating principle of single phase induction motors; Synchronous machines: cylindrical and salient pole machines, performance, regulation and parallel operation of generators, starting of synchronous motor, characteristics; Types of losses and efficiency calculations of electric machines.

Section 6: Power Systems

Power generation concepts, ac and dc transmission concepts, Models and performance of transmission lines and cables, Series and shunt compensation, Electric field distribution and insulators, Distribution systems, Per-unit quantities, bus admittance matrix, Gauss-Seidel and Newton-Raphson load flow methods, Voltage and Frequency control, Power factor correction, Symmetrical components, Symmetrical and unsymmetrical fault analysis, Principles of over-current, differential and distance protection; Circuit breakers, System stability concepts, Equal area criterion.

Section 7: Control Systems

Mathematical modeling and representation of systems, Feedback principle, transfer function, Block diagrams and Signal flow graphs, Transient and Steady-state analysis of linear time invariant systems, Routh-Hurwitz and Nyquist criteria, Bode plots, Root loci, Stability analysis, Lag, Lead and Lead-Lag compensators; P, PI and PID controllers; State space model, State transition matrix.

Section 8: Electrical and Electronic Measurements

Bridges and Potentiometers, Measurement of voltage, current, power, energy and power factor; Instrument transformers, Digital voltmeters and multimeters, Phase, Time and Frequency measurement; Oscilloscopes, Error analysis.

Section 9: Analog and Digital Electronics

Characteristics of diodes, BJT, MOSFET; Simple diode circuits: clipping, clamping, rectifiers; Amplifiers: Biasing, Equivalent circuit and Frequency response; Oscillators and Feedback amplifiers; Operational amplifiers: Characteristics and applications; Simple active filters, VCOs and Timers, Combinational and Sequential logic circuits, Multiplexer, Demultiplexer, Schmitt trigger, Sample and hold circuits, A/D and D/A converters, 8085 Microprocessor: Architecture, Programming and Interfacing.

Section 10: Power Electronics

Characteristics of semiconductor power devices: Diode, Thyristor, Triac, GTO, MOSFET, IGBT; DC to DC conversion: Buck, Boost and Buck-Boost converters; Single and three phase configuration of uncontrolled rectifiers, Line commutated thyristor based converters, Bidirectional ac to dc voltage source converters, Issues of line current harmonics, Power factor, Distortion factor of ac to dc converters, Single phase and three phase inverters, Sinusoidal pulse width modulation.

MECHANICAL DISCIPLINE

Section 1: Engineering Mathematics

Linear Algebra: Matrix algebra, systems of linear equations, eigenvalues and eigenvectors.

Calculus: Functions of single variable, limit, continuity and differentiability, mean value theorems, indeterminate forms; evaluation of definite and improper integrals; double and triple integrals; partial derivatives, total derivative, Taylor series (in one and two variables), maxima and minima, Fourier series; gradient, divergence and curl, vector identities, directional derivatives, line, surface and volume integrals, applications of Gauss, Stokes and Green's theorems.

Differential equations: First order equations (linear and nonlinear); higher order linear differential equations with constant coefficients; Euler-Cauchy equation; initial and boundary value problems; Laplace transforms; solutions of heat, wave and Laplace's equations.

Complex variables: Analytic functions; Cauchy-Riemann equations; Cauchy's integral theorem and integral formula; Taylor and Laurent series.

Probability and Statistics: Definitions of probability, sampling theorems, conditional probability; mean, median, mode and standard deviation; random variables, binomial, Poisson and normal distributions.

Numerical Methods: Numerical solutions of linear and non-linear algebraic equations; integration by trapezoidal and Simpson's rules; single and multi-step methods for differential equations.

Section 2: Applied Mechanics and Design

Engineering Mechanics: Free-body diagrams and equilibrium; trusses and frames; virtual work; kinematics and dynamics of particles and of rigid bodies in plane motion; impulse and momentum (linear and angular) and energy formulations, collisions.

Mechanics of Materials: Stress and strain, elastic constants, Poisson's ratio; Mohr's circle for plane stress and plane strain; thin cylinders; shear force and bending moment diagrams; bending and shear stresses; deflection of beams; torsion of circular shafts; Euler's theory of columns; energy methods; thermal stresses; strain gauges and rosettes; testing of materials with universal testing machine; testing of hardness and impact strength.

Theory of Machines: Displacement, velocity and acceleration analysis of plane mechanisms; dynamic analysis of linkages; cams; gears and gear trains; flywheels and governors; balancing of reciprocating and rotating masses; gyroscope.

Vibrations: Free and forced vibration of single degree of freedom systems, effect of damping; vibration isolation; resonance; critical speeds of shafts.

Machine Design: Design for static and dynamic loading; failure theories; fatigue strength and the S-N diagram; principles of the design of machine elements such as bolted, riveted and welded joints; shafts, gears, rolling and sliding contact bearings, brakes and clutches, springs.

Section 3: Fluid Mechanics and Thermal Sciences

Fluid Mechanics: Fluid properties; fluid statics, manometry, buoyancy, forces on submerged bodies, stability of floating bodies; control-volume analysis of mass, momentum and energy; fluid acceleration; differential equations of continuity and momentum; Bernoulli's equation; dimensional analysis; viscous flow of incompressible fluids, boundary layer, elementary turbulent flow, flow through pipes, head losses in pipes, bends and fittings.

Heat-Transfer: Modes of heat transfer; one dimensional heat conduction, resistance concept and electrical analogy, heat transfer through fins; unsteady heat conduction, lumped parameter system, Heisler's charts; thermal boundary layer, dimensionless parameters in free and forced convective heat transfer, heat transfer correlations for flow over flat plates and through pipes, effect of turbulence; heat exchanger performance, LMTD and NTU methods; radiative heat transfer, Stefan- Boltzmann law, Wien's displacement law, black and grey surfaces, view factors, radiation network analysis.

Thermodynamics: Thermodynamic systems and processes; properties of pure substances, behavior of ideal and real gases; zeroth and first laws of thermodynamics, calculation of work and heat in various processes; second law of thermodynamics; thermodynamic property charts and tables, availability and irreversibility; thermodynamic relations.

Applications: *Power Engineering*: Air and gas compressors; vapour and gas power cycles, concepts of regeneration and reheat. *I.C. Engines*: Air-standard Otto, Diesel and dual cycles. *Refrigeration and air-conditioning*: Vapour and gas refrigeration and heat pump cycles; properties of moist air, psychrometric chart, basic psychrometric processes. *Turbo machinery*: Impulse and reaction principles, velocity diagrams, Pelton-wheel, Francis and Kaplan turbines.

Section 4: Materials, Manufacturing and Industrial Engineering

Engineering Materials: Structure and properties of engineering materials, phase diagrams, heat treatment, stress-strain diagrams for engineering materials.

Casting, Forming and Joining Processes: Different types of castings, design of patterns, moulds and cores; solidification and cooling; riser and gating design. Plastic deformation and yield criteria; fundamentals of hot and cold working processes; load estimation for bulk (forging, rolling, extrusion, drawing) and sheet

(shearing, deep drawing, bending) metal forming processes; principles of powder metallurgy. Principles of welding, brazing, soldering and adhesive bonding.

Machining and Machine Tool Operations: Mechanics of machining; basic machine tools; single and multi-point cutting tools, tool geometry and materials, tool life and wear; economics of machining; principles of non-traditional machining processes; principles of work holding, design of jigs and fixtures.

Metrology and Inspection: Limits, fits and tolerances; linear and angular measurements; comparators; gauge design; interferometry; form and finish measurement; alignment and testing methods; tolerance analysis in manufacturing and assembly.

Computer Integrated Manufacturing: Basic concepts of CAD/CAM and their integration tools.

Production Planning and Control: Forecasting models, aggregate production planning, scheduling, materials requirement planning.

Inventory Control: Deterministic models; safety stock inventory control systems.

Operations Research: Linear programming, simplex method, transportation, assignment, network flow models, simple queuing models, PERT and CPM.

ELECTRONICS DISCIPLINE

Section 1: Engineering Mathematics

Linear Algebra: Vector space, basis, linear dependence and independence, matrix algebra, eigenvalues and eigen vectors, rank, solution of linear equations – existence and uniqueness.

Calculus: Mean value theorems, theorems of integral calculus, evaluation of definite and improper integrals, partial derivatives, maxima and minima, multiple integrals, line, surface and volume integrals, Taylor series.

Differential Equations: First order equations (linear and nonlinear), higher order linear differential equations, Cauchy's and Euler's equations, methods of solution using variation of parameters, complementary function and particular integral, partial differential equations, variable separable method, initial and boundary value problems.

Vector Analysis: Vectors in plane and space, vector operations, gradient, divergence and curl, Gauss's, Green's and Stoke's theorems.

Complex Analysis: Analytic functions, Cauchy's integral theorem, Cauchy's integral formula; Taylor's and Laurent's series, residue theorem.

Numerical Methods: Solution of nonlinear equations, single and multi-step methods for differential equations, convergence criteria.

Probability and Statistics: Mean, median, mode and standard deviation; combinatorial probability, probability distribution functions - binomial, Poisson, exponential and normal; Joint and conditional probability; Correlation and regression analysis.

Section 2: Networks, Signals and Systems

Network solution methods: nodal and mesh analysis; Network theorems: superposition, Thevenin and Norton's, maximum power transfer; Wye - Delta transformation; Steady state sinusoidal analysis using phasors; Time domain analysis of simple linear circuits; Solution of network equations using Laplace transform; Frequency domain analysis of RLC circuits; Linear 2 - port network parameters: driving point and transfer functions; State equations for networks.

Continuous-time signals: Fourier series and Fourier transform representations, sampling theorem and applications; Discrete-time signals: discrete-time Fourier transform (DTFT), DFT, FFT, Z-transform, interpolation of discrete-time signals; LTI systems: definition and properties, causality, stability, impulse response, convolution, poles and zeros, parallel and cascade structure, frequency response, group delay, phase delay, digital filter design techniques.

Section 3: Electronic Devices

Energy bands in intrinsic and extrinsic silicon; Carrier transport: diffusion current, drift current, mobility and resistivity; Generation and recombination of carriers; Poisson and continuity equations; P-N junction, Zener diode, BJT, MOS capacitor, MOSFET, LED, photo diode and solar cell; Integrated circuit fabrication process: oxidation, diffusion, ion implantation, photolithography and twin-tub CMOS process.

Section 4: Analog Circuits

Small signal equivalent circuits of diodes, BJTs and MOSFETs; Simple diode circuits: clipping, clamping and rectifiers; Single-stage BJT and MOSFET amplifiers: biasing, bias stability, midfrequency small signal analysis and frequency response; BJT and MOSFET amplifiers: multi-stage, differential, feedback, power and operational; Simple op-amp circuits; Active filters; Sinusoidal oscillators: criterion for oscillation, single-transistor and op- amp configurations; Function generators, wave-shaping circuits and 555 timers; Voltage reference circuits; Power supplies: ripple removal and regulation.

Section 5: Digital Circuits

Number systems; Combinatorial circuits: Boolean algebra, minimization of functions using Boolean identities and Karnaugh map, logic gates and their static CMOS implementations, arithmetic circuits, code converters, multiplexers, decoders and PLAs; Sequential circuits: latches and flip - flops, counters, shift - registers and finite state machines; Data converters: sample and hold circuits, ADCs and DACs; Semiconductor memories: ROM, SRAM, DRAM; 8-bit microprocessor (8085): architecture, programming, memory and I/O interfacing.

Section 6: Control Systems

Basic control system components; Feedback principle; Transfer function; Block diagram representation; Signal flow graph; Transient and steady-state analysis of LTI systems; Frequency response; Routh-Hurwitz and Nyquist stability criteria; Bode and root-locus plots; Lag, lead and lag-lead compensation; State variable model and solution of state equation of LTI systems.

Section 7: Communications

Random processes: autocorrelation and power spectral density, properties of white noise, filtering of random signals through LTI systems; Analog communications: amplitude modulation and demodulation, angle modulation and demodulation, spectra of AM and FM, superheterodyne receivers, circuits for analog communications; Information theory: entropy, mutual information and channel capacity theorem; Digital communications: PCM, DPCM, digital modulation schemes, amplitude, phase and frequency shift keying (ASK, PSK, FSK), QAM, MAP and ML decoding, matched filter receiver, calculation of bandwidth, SNR and BER for digital modulation; Fundamentals of error correction, Hamming codes; Timing and frequency synchronization, inter-symbol interference and its mitigation; Basics of TDMA, FDMA and CDMA.

Section 8: Electromagnetics

Electrostatics; Maxwell's equations: differential and integral forms and their interpretation, boundary conditions, wave equation, Poynting vector; Plane waves and properties: reflection and refraction, polarization, phase and group velocity, propagation through various media, skin depth; Transmission lines: equations, characteristic impedance, impedance matching, impedance transformation, Sparameters, Smith chart; Waveguides: modes, boundary conditions, cut-off frequencies, dispersion relations; Antennas: antenna types, radiation pattern, gain and directivity, return loss, antenna arrays; Basics of radar; Light propagation in optical fibers.

INSTRUMENTATION DISCIPLINE

Section 1: Engineering Mathematics

Linear Algebra: Matrix algebra, systems of linear equations, Eigen values and Eigen vectors. Calculus: Mean value theorems, theorems of integral calculus, partial derivatives, maxima and minima, multiple integrals, Fourier series, vector identities, line, surface and volume integrals, Stokes, Gauss and Green's theorems.

Differential equations: First order equation (linear and nonlinear), higher order linear differential equations with constant coefficients, method of variation of parameters, Cauchy's and Euler's equations, initial and boundary value problems, solution of partial differential equations: variable separable method.

Analysis of complex variables: Analytic functions, Cauchy's integral theorem and integral formula, Taylor's and Laurent's series, residue theorem, solution of integrals.

Probability and Statistics: Sampling theorems, conditional probability, mean, median, mode and standard deviation, random variables, discrete and continuous distributions: normal, Poisson and binomial distributions.

Numerical Methods: Matrix inversion, solutions of non-linear algebraic equations, iterative methods for solving differential equations, numerical integration, regression and correlation analysis.

Instrumentation Engineering

Section 2: Electrical Circuits

Voltage and current sources: independent, dependent, ideal and practical; v-i relationships of resistor, inductor, mutual inductor and capacitor; transient analysis of RLC circuits with dc excitation.

Kirchoff's laws, mesh and nodal analysis, superposition, Thevenin, Norton, maximum power transfer and reciprocity theorems.

Peak-, average- and rms values of ac quantities; apparent-, active- and reactive powers; phasor analysis, impedance and admittance; series and parallel resonance, locus diagrams, realization of basic filters with R, L and C elements.

One-port and two-port networks, driving point impedance and admittance, open-, and short circuit parameters.

Section 3: Signals and Systems

Periodic, aperiodic and impulse signals; Laplace, Fourier and z-transforms; transfer function, frequency response of first and second order linear time invariant systems, impulse response of systems; convolution, correlation. Discrete time system: impulse response, frequency response, pulse transfer function; DFT and FFT; basics of IIR and FIR filters.

Section 4: Control Systems

Feedback principles, signal flow graphs, transient response, steady-state-errors, Bode plot, phase and gain margins, Routh and Nyquist criteria, root loci, design of lead, lag and lead-lag compensators, state-space representation of systems; time-delay systems; mechanical, hydraulic and pneumatic system components, synchro pair, servo and stepper motors, servo valves; on-off, P, P-I, P-I-D, cascade, feedforward, and ratio controllers.

Section 5: Analog Electronics

Characteristics and applications of diode, Zener diode, BJT and MOSFET; small signal analysis of transistor circuits, feedback amplifiers. Characteristics of operational amplifiers; applications of opamps: difference amplifier, adder, subtractor, integrator, differentiator, instrumentation amplifier, precision rectifier, active filters and other circuits. Oscillators, signal generators, voltage controlled oscillators and phase locked loop.

Section 6: Digital Electronics

Combinational logic circuits, minimization of Boolean functions. IC families: TTL and CMOS. Arithmetic circuits, comparators, Schmitt trigger, multi-vibrators, sequential circuits, flip-flops, shift registers, timers and counters; sample-and-hold circuit, multiplexer, analog-to-digital (successive approximation, integrating, flash and sigma-delta) and digital-to analog converters (weighted R, R-2R ladder and current steering logic). Characteristics of ADC and DAC (resolution, quantization, significant bits, conversion/settling time); basics of number systems, 8-bit microprocessor and microcontroller: applications, memory and input-output interfacing; basics of data acquisition systems.

Section 7: Measurements

SI units, systematic and random errors in measurement, expression of uncertainty - accuracy and precision index, propagation of errors. PMMC, MI and dynamometer type instruments; dc potentiometer; bridges for measurement of R, L and C, Q-meter. Measurement of voltage, current and power in single and three phase circuits; ac and dc current probes; true rms meters, voltage and current scaling, instrument transformers, timer/counter, time, phase and frequency measurements, digital voltmeter, digital multimeter; oscilloscope, shielding and grounding.

Section 8: Sensors and Industrial Instrumentation

Resistive-, capacitive-, inductive-, piezoelectric-, Hall effect sensors and associated signal conditioning circuits; transducers for industrial instrumentation: displacement (linear and angular), velocity, acceleration, force, torque, vibration, shock, pressure (including low pressure), flow (differential pressure, variable area, electromagnetic, ultrasonic, turbine and open channel flow meters) temperature (thermocouple, bolometer, RTD (3/4 wire), thermistor, pyrometer and semiconductor); liquid level, pH, conductivity and viscosity measurement.

Section 9: Communication and Optical Instrumentation

Amplitude- and frequency modulation and demodulation; Shannon's sampling theorem, pulse code modulation; frequency and time division multiplexing, amplitude-, phase-, frequency-, pulse shift keying for digital modulation; optical sources and detectors: LED, laser, photo-diode, light dependent resistor and their characteristics; interferometer: applications in metrology; basics of fiber optic sensing.
